

Introduction to Stateflow (for MATLAB)

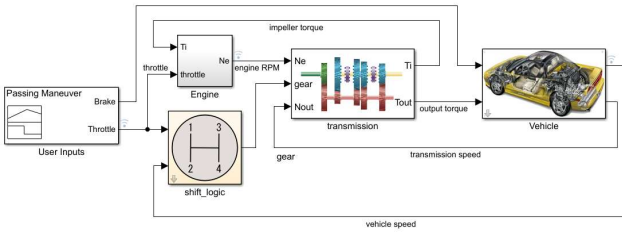
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Why use State Machines

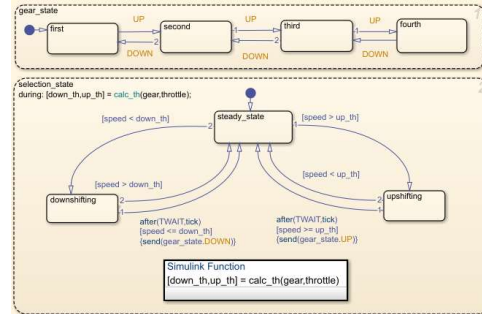
A state transition diagrams can serve as a high-level starting point for a complex software design process.

This can prove a far more effective development strategy than diving straight into writing thousands of lines of code

Simulink and Stateflow are a powerful combination



Simulink is used to respond to **continuous** changes



Stateflow is used to respond to **discrete** changes

Simulink and Stateflow are a powerful combination

Systems need to respond to both **continuous** and **discrete** changes



Continuous	Suspension dynamics
Discrete	Gear changes



Continuous	Propulsion system
Discrete	Liftoff stages



Continuous	Rotational movement
Discrete	Operational modes

What we'll cover during this session

- State Machines in a nutshell
- Why use State machines
- When to use Stateflow for designing logic
- Harel charts
 - Hierarchy
 - Parallelism
 - Broadcasting
- Examples
- Questions



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Messaggio

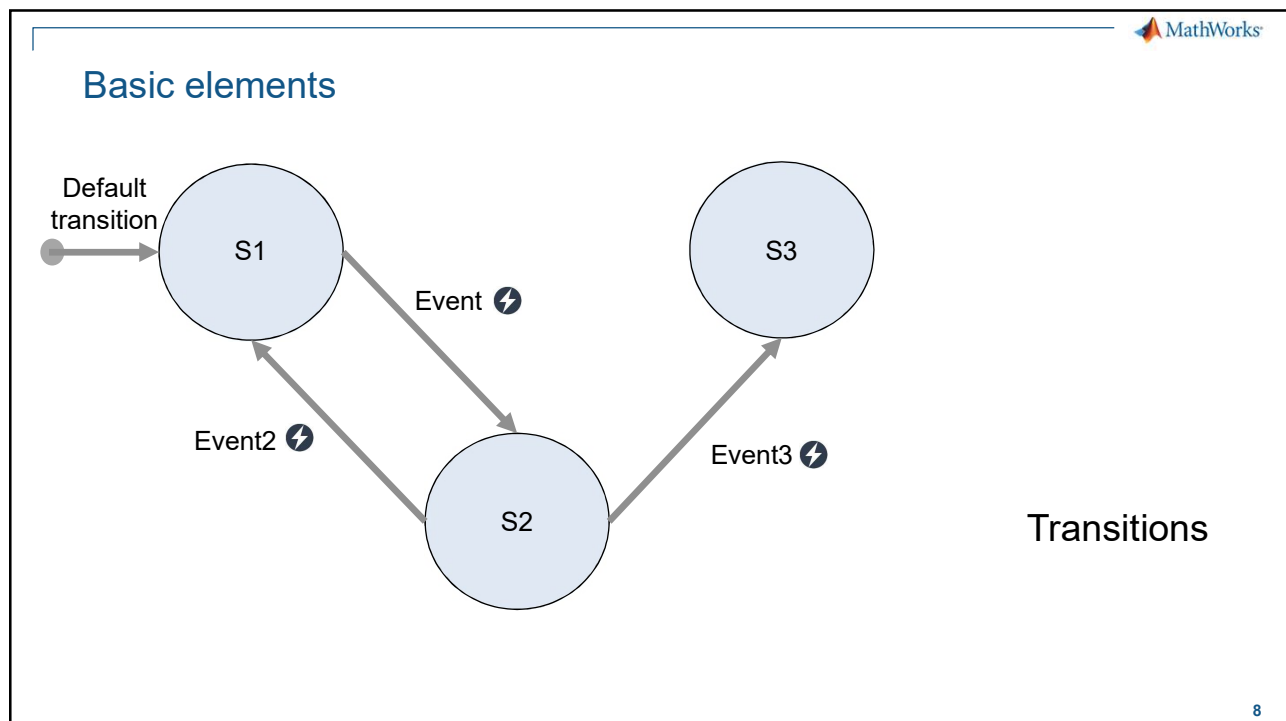
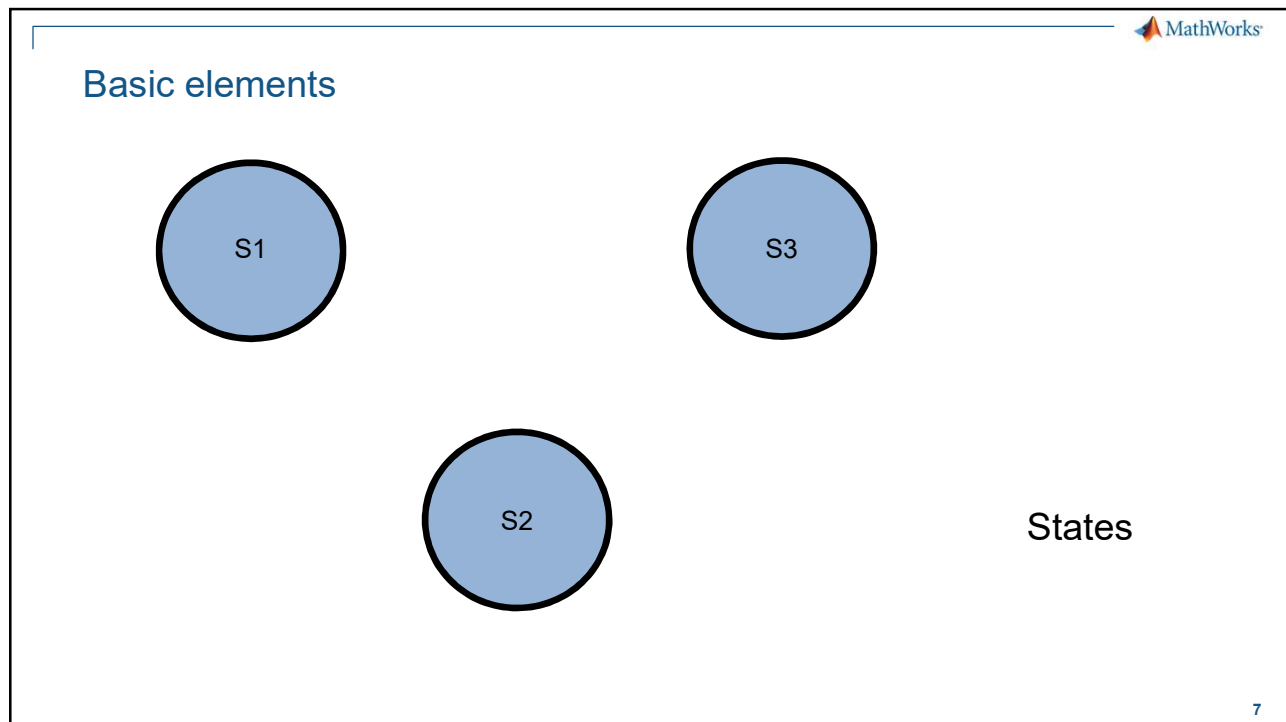
Vis

State Machines in a nutshell

A finite state machine is a **method** of modeling a system comprised of a **limited** number of modes: depending on which mode it's in, the machine will behave in one manner or another.

And while finite state machines can be used to describe items both natural and manmade, for historical reasons the term most commonly refers to **computing systems**.

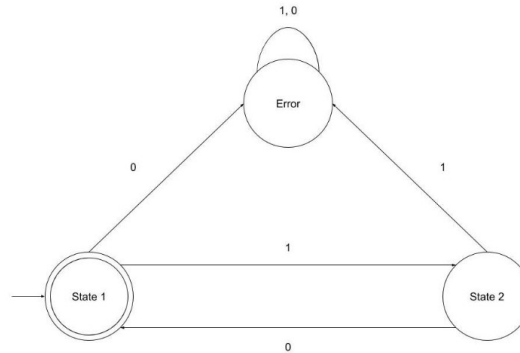
Now there are many ways of expressing finite state machines, though a **graphical approach** is often the one taken.



Let's create a Finite State Machine that parses a sequence that:

- starts with 1
- every 1 must be followed by 0
- every 0 must be followed by 1

For example, 1010 is a valid input sequence but 110 and 10100 are not.



```

def watch(self, current_state, state_input):
    """Determines if the state and the input satisfies this transition relation"""
    return self.current_state == current_state and self.state_input == state_input

class FSM:
    """A basic model of computation"""
    def __init__(
        self,
        states=[],
        alphabet=[],
        accepting_states=[],
        initial_state=""
    ):
        self.states = states
        self.alphabet = alphabet
        self.accepting_states = accepting_states
        self.initial_state = initial_state
        self.valid_transitions = False

    def set_transitions(self, transitions=[]):
        """Before we use a list of transitions, verify they only apply to our states"""
        for transition in transitions:
            if transition.current_state not in self.states:
                print(
                    "Invalid transition. {} is not a valid state".format(
                        transition.current_state)
                )
                return
            if transition.next_state not in self.states:
                print("Invalid transition. {} is not a valid state".format(
                    transition.next_state))
                return
            self.transitions = transitions
            self.valid_transitions = True

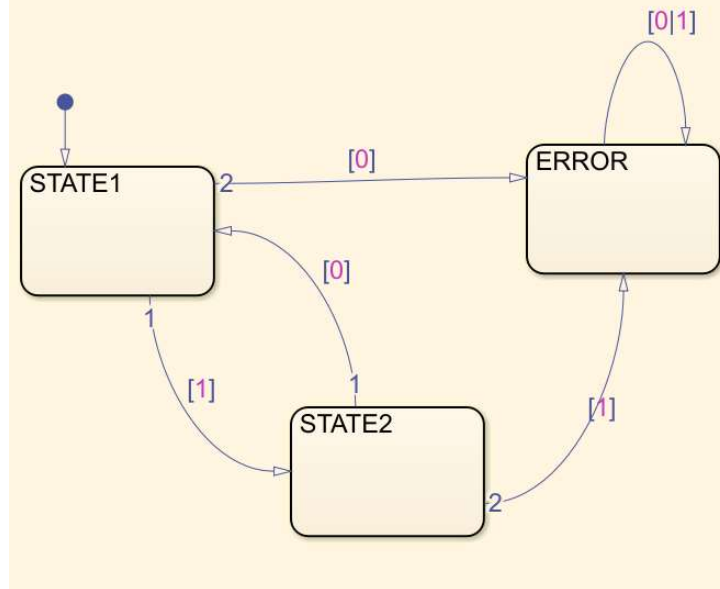
    def __accept(self, current_state, state_input):
        """Look to see if the input for the given state matches a transition rule"""
        if not self.valid_transitions:
            return None
        for rule in self.transitions:
            if rule.matches(current_state, state_input):
                return rule.next_state
        print("No transition for state and input")
        return None

    def accepts(self, sequence):
        """Process an input stream to determine if the FSM will accept it"""
        # Check if we have transitions
        if not self.valid_transitions:
            print("Cannot process sequence without valid transitions")
            return False
        print("Starting at {}".format(self.initial_state))
        # Check to make sure we're processing the right state of the initial state
        if self.initial_state not in self.states:
            return False
        if len(sequence) == 0:
            return self.initial_state in self.accepting_states

        # Start processing the initial state
        current_state = self.__accept(self.initial_state, sequence[0])
        if current_state is None:
            return False

        # Continue with the rest of the sequence
        for state_input in sequence[1:]:
            print("Current state is {}".format(current_state))
            current_state = self.__accept(current_state, state_input)
            if current_state is None:
                return False

        print("Ending state is {}".format(current_state))
        # Check if the state is an accepting state
        return current_state in self.accepting_states
    
```



That state machine in a traditional programming language
<https://stackabuse.com/theory-of-computation-finite-state-machines/>

The same state machine in Stateflow

Why not just use MATLAB to design logic?

For simple logic, just use MATLAB

```
if u >= t
    y = u;
else
    y = 0;
end
```

But for logic that is more complex, Stateflow is the best tool to use

- By the way, even simple logic can often get complex

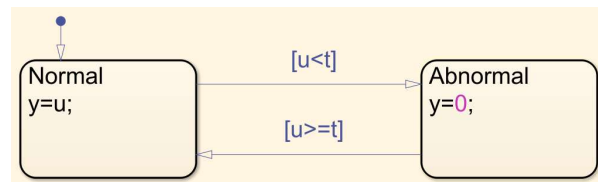
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Comparing MATLAB and Stateflow for Designing Logic

Task: Create simple logic

Identify places in data where values are above a threshold t

```
for i = 1:length(inData)
    if(inData(i) >= t)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end
```



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Comparing MATLAB and Stateflow for Designing Logic

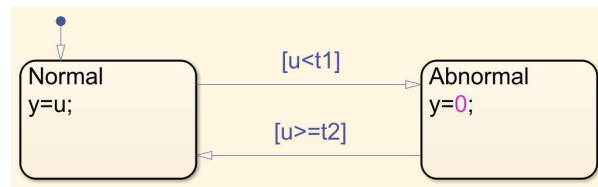
Task: Add hysteresis

Identify places in data where values are below t1 and above t2

```

inNormalRegion = true;
for i = 1:length(inData)
    if(inNormalRegion && (inData(i)<t1))
        inNormalRegion = false;
    elseif(~inNormalRegion && (inData(i)>=t2))
        inNormalRegion = true;
    end
    if(inNormalRegion)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end
end

```



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Comparing MATLAB and Stateflow for Designing Logic

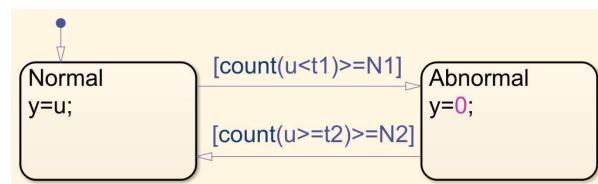
Task: Add debouncing

Identify places in data where values are below t1 for at least N1 samples and above t2 for at least N2 samples

```

inNormalRegion = true;
counter = 0;
for i=1:length(inData)
    if(inNormalRegion)
        if(inData(i)<t1)
            counter = counter+1;
            if(counter>=N1)
                inNormalRegion = false;
            end
        else
            counter = 0;
        end
    else
        if(inData(i)>=t2)
            counter = counter+1;
            if(counter>=N2)
                inNormalRegion = true;
            end
        else
            counter = 0;
        end
    end
end
end

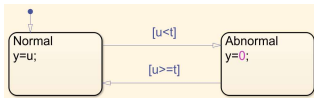
```



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MATLAB code expands, while Stateflow chart remains compact

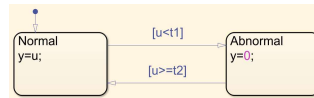
simple logic



```

for i = 1:length(inData)
    if(inData(i) >= t)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end
  
```

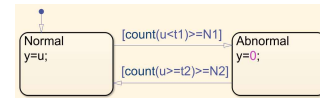
+ hysteresis



```

inNormalRegion = true;
for i = 1:length(inData)
    if(inNormalRegion && (inData(i)<t1))
        inNormalRegion = false;
    elseif(~inNormalRegion && (inData(i)>=t2))
        inNormalRegion = true;
    end
    if(inNormalRegion)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end
  
```

+ hysteresis + debouncing



```

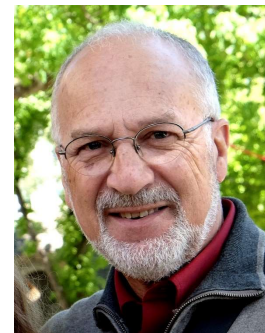
inNormalRegion = true;
counter = 0;
for i=1:length(inData)
    if(inNormalRegion)
        if(inData(i)<t1)
            counter = counter+1;
            if(counter>=N1)
                inNormalRegion = false;
            end
        else
            counter = 0;
        end
    else
        if(inData(i)>=t2)
            counter = counter+1;
            if(counter>=N2)
                inNormalRegion = true;
            end
        else
            counter = 0;
        end
    end
    if(inNormalRegion)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end
  
```

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In the 1980s, Dr. David Harel took a fresh look at finite state machines and realized that state transition diagrams were an excellent way of expressing the logic of avionics systems.

In order to get everything he wanted, he had to expand their semantic with three new concepts:

- Parallelism
- Hierarchy
- Event broadcast

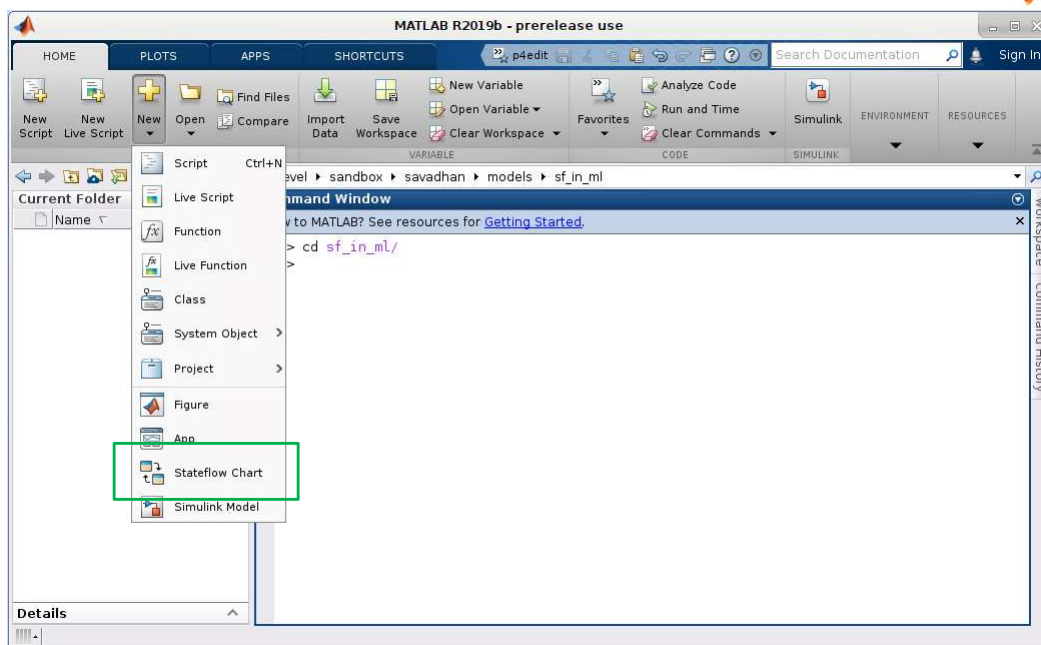


These enhanced diagrams were called *statecharts*

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```
>> sldemo_fuelsys
```

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The screenshot shows the MATLAB Stateflow editor for a chart named 'dataScrubber'. The chart contains two states: 'Positive' with the execution function `y = 1;` and 'Negative' with the execution function `y = -1;`. Transitions between states are triggered by the conditions `[count(u < 0) > 3]` (from Positive to Negative) and `[count(u > 0) > 3]` (from Negative to Positive). The interface includes a Command Window, a Symbol palette, and various toolbars for modeling and execution.

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This screenshot shows the same Stateflow chart as in slide 19, but with the Command Window open. The Command Window displays the following MATLAB code and its output:

```
>> c = dataScrubber('u', 0)
c =
Stateflow Chart
Execution Function
    step(c, Name, Value)
Local Data
    u      : 0
    y      : 1
Active States: {'Positive'}
```

The Command Window also shows the prompt `fx >>` and a link to 'Getting Started' resources. The Stateflow chart in the background remains the same, with the 'Positive' state highlighted by a blue border.

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The screenshot shows the MATLAB Stateflow environment. The Stateflow chart, titled 'dataScrubber', consists of two states: 'Positive' (containing $y = 1;$) and 'Negative' (containing $y = -1;$). Transitions are triggered by the conditions $[\text{count}(u < 0) > 3]$ and $[\text{count}(u > 0) > 3]$. The Command Window shows the following code and output:

```

>> c = dataScrubber('u', 0)
c =
Stateflow Chart
Execution Function
  step(c, Name, Value)
Local Data
  u      : 0
  y      : 1
Active States: {'Positive'}
>>
>> step(c, 'u', -1)
fx >>
  
```

The 'Positive' state is highlighted with a blue border. The simulation progress bar at the bottom indicates 194% completion.

21

The screenshot shows the MATLAB Stateflow environment. The Stateflow chart, titled 'dataScrubber', consists of two states: 'Positive' (containing $y = 1;$) and 'Negative' (containing $y = -1;$). Transitions are triggered by the conditions $[\text{count}(u < 0) > 3]$ and $[\text{count}(u > 0) > 3]$. The Command Window shows the following code and output:

```

c =
Stateflow Chart
Execution Function
  step(c, Name, Value)
Local Data
  u      : 0
  y      : 1
Active States: {'Positive'}
>>
>> step(c, 'u', -1)
>> step(c, 'u', -1)
>> step(c, 'u', -1)
>> step(c, 'u', -1)
fx >>
  
```

The 'Negative' state is highlighted with a blue border. The simulation progress bar at the bottom indicates 194% completion.

22

The image shows the MATLAB Stateflow environment. On the left, the Command Window displays the following MATLAB code and output:

```

y      : 1
Active States: {'Positive'}
>>
>> step(c, 'u', -1)
>> step(c, 'u', -1)
>> step(c, 'u', -1)
>> step(c, 'u', -1)
>> disp(c)
Stateflow Chart

Execution Function
step(c, Name, Value)
Local Data
u      : -1
y      : -1
Active States: {'Negative'}
fx >>
    
```

On the right, the Stateflow chart shows two states: 'Positive' (containing $y = 1;$) and 'Negative' (containing $y = -1;$). Transitions are labeled with conditions: $[count(u < 0) > 3]$ from Positive to Negative, and $[count(u > 0) > 3]$ from Negative to Positive.

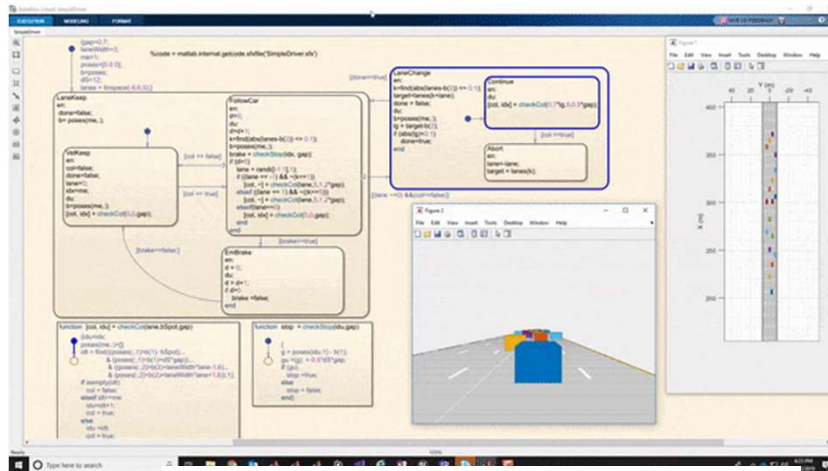
Uses of Stateflow in MATLAB

- Test and Measurement
 - Detecting a data stream trigger

The image displays the 'Analog Trigger App Example' in MATLAB. On the left, there are configuration panels for 'Device' (Audio [HP 4120 Microp...]), 'Measurement Type' (Audio), 'Range' (-1.00 to 1.00), and 'Rate (samples)' (44100). Below these are two plots: 'Live Data' and 'Captured Data', both showing 'Normalized amplitude' vs 'Time (s)'. On the right, the Stateflow chart for 'AnalogTriggerAppChart' is shown, featuring states for 'Device Selection', 'Buffering', 'Capture', and 'Capturing Data', with various transitions and actions.

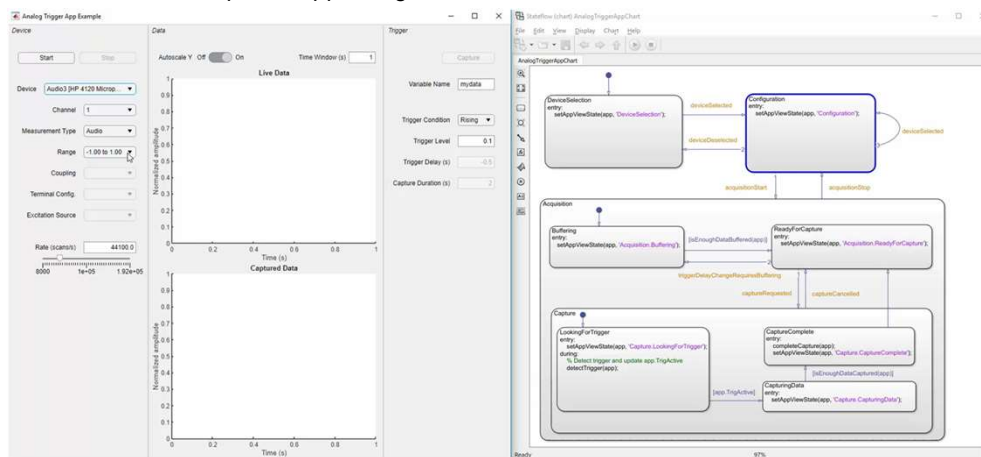
Some other examples

- Robotics and autonomous systems engineers
 - Design path planning, path following, and obstacle avoidance algorithms



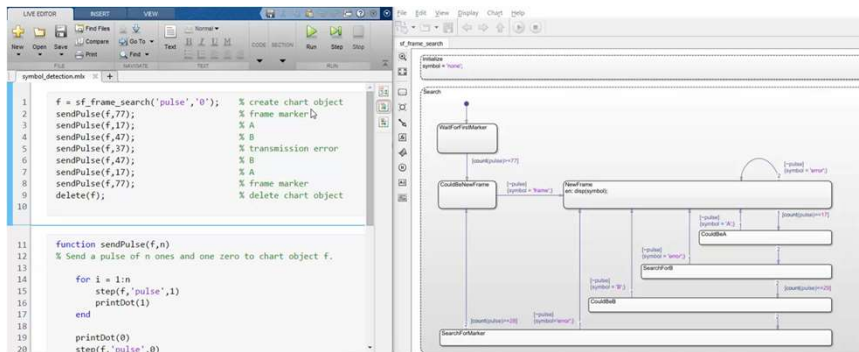
Who gets most value in using state machines

- UI developers
 - Control UI's developed in App Designer and GUIDE



Who gets most value in using state machines

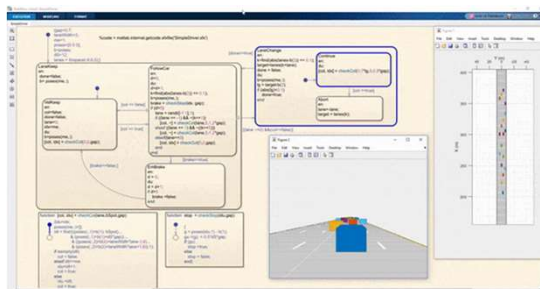
- UI developers
 - Control UI's developed in App Designer
- Communications engineers
 - Analyze streams of communication data and model communication protocols



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Who gets most value in using state machines

- UI developers
 - Control UI's developed in App Designer and GUIDE
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- Robotics and autonomous systems engineers
 - Design path planning, path following, and obstacle avoidance algorithms



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Who gets most value in using state machines

- UI developers
 - Control UI's developed in App Designer and GUIDE
- Communications engineers
 - Analyze streams of communication data and model communication protocols
- Robotics and autonomous systems engineers
 - Design path planning, path following, and obstacle avoidance algorithms
- ADAS engineers
 - Analyze sensor data and apply ground truth labeling algorithms
- Radar engineers
 - Analyze streams of data coming from radar systems
- Test systems engineers
 - Monitor I/O of systems and analyze various modes of operation

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Many examples included in shipping documentation

Getting started tutorials

Create Stateflow Charts for Execution as MATLAB Objects

Save standalone Stateflow charts outside of Simulink® models.

Execute and Unit Test Stateflow Chart Objects

Run Stateflow charts in MATLAB or through the Stateflow editor.

Debug a Standalone Stateflow Chart

Interrupt execution to step through each action in a Stateflow chart.

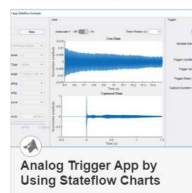
Execute Stateflow Chart Objects Through Scripts and Models

Create a MATLAB script or a Simulink model that invokes a standalone Stateflow chart.

Application examples

- Connecting to App Designer
- Communications example
- Comp finance example
- Data acquisition example

Featured Examples



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Question?

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Thanks!

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